

Geometric considerations in virus capsid size specificity, auxiliary requirements, and buckling

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Spherical capsids are shells of protein subunits that protect the genomes of many viral strains. Although nature displays a range of spherical capsid sizes (reflected by the number of subunits in the formation), specific strains display stringent requirements for forming capsids of specific sizes, a requirement that appears crucial to infectivity. Despite its importance in pathogenicity, little is known regarding the determinants of capsid size. Still less is known about exactly which capsids can undergo maturation events such as buckling transitions—postcapsid-assembly events that are crucial to some virus strains. We show that the exclusive determinant of capsid size is hexamer shape, as defined by subunit–subunit dihedral angles. This conclusion arises from considering the dihedral angle patterns within hexamers belonging to natural canonical capsids and geometric capsid models (deltahedra). From simple geometric models and an understanding of endo angle propagation discussed here, we then suggest that buckling transitions may be available only to capsids of certain size (specifically, $T < 7$ capsids are precluded from such transformations) and that $T > 7$ capsids require the help of auxiliary mechanisms for proper capsid formation. These predictions, arising from simple geometry and modeling, are backed by a body of empirical evidence, further reinforcing the extent to which the evolution of the atomistically complex virus capsid may be principled around simple geometric design/requirements.

auxiliary proteins | capsid buckling | deltahedra | endo angle constraint

A large number of human- and crop-infecting viruses are protected by spherical capsids (shells) of various sizes that are primarily made up of self-organizing protein subunits (1, 2). Caspar and Klug's (3) seminal article on quasi-equivalence explained how an infinite range of capsid sizes can be “constructed” by combining $60T$ subunits or 12 pentamers (5-valent subunit clusters) and a variable number of hexamers [$10 \times (T - 1)$] into a closed spherical shell ($T \in \{1, 3, 4, 7, \dots\}$) and is the triangulation number described in ref. 3).

From the range of possible sizes, generally, subunits from specific viral strains assemble into capsids of specific sizes; the inability to form those native sizes is believed to result in the loss of infectivity. For example, the sobemovirus and birnavirus capsids (4, 5) shown in Fig. 1A are known to be pathogenic primarily in their native $T = 3$ and $T = 13$ capsid forms, respectively. Despite its importance in pathogenicity, our picture of capsid size specificity is incomplete. In the present report, we are interested in the structural features (constraints), if any exist, that differentiate between capsids of different sizes (capsid design criteria). An appreciation of these concepts is pressing from a nanotechnological perspective [for the rational design of artificial scalable assemblies that build on current practices, such as in the use of protein fusion and symmetry properties by Padilla et al. (6)] and a therapeutic perspective (to impede the formation of infective native capsids).

The size-specificity puzzle gets more interesting given the theoretical evidence that a single subunit shape (the trapezoidal prototile) possesses the ability to tile all of the allowed canonical

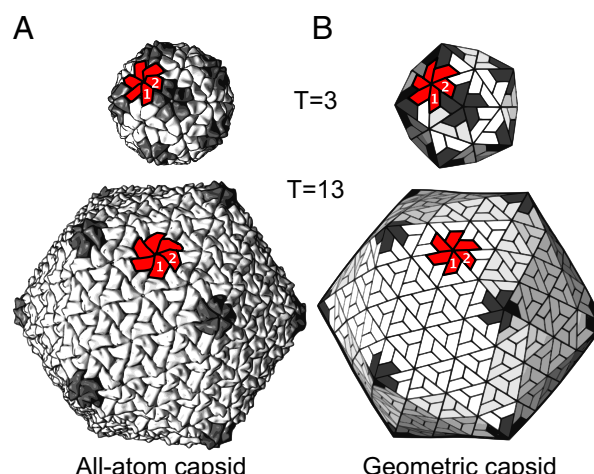


Fig. 1. Spherical canonical capsids are scalable. (A) Two natural canonical capsids (the $T = 3$ sobemovirus and $T = 13$ birnavirus capsids with PDB IDs codes 1smv and 1wce, respectively) are shown to emphasize that spherical capsids come in many sizes that are composed of 12 pentamers (dark gray) and $10 \times (T - 1)$ hexamers (3). (B) We use geometric models as platonic capsid representations for the characterization of structure and function. In each capsid, a single hexamer (colored red) along with 2 subunits (“1” and “2”) are marked to emphasize the structural correspondence between all-atom and geometric capsids.

capsid sizes ($T = 1, 3, 4, 7, \dots$) (7), which is backed by evidence of a ubiquitous trapezoidal subunit shape seen in nature (discussed in ref. 8). In these situations, the differences between capsids of different sizes will be seen within the capsid's subunit–subunit dihedral angles,* i.e., size-specificity within canonical capsids (7) may be manifested in the angles at which the generally rigid subunits interact within the capsid.

In the following sections, we attempt to show that the exclusive determinant of canonical capsid size is hexamer shape as defined by the internal subunit–subunit dihedral angles that comprise the hexameric capsomers. We then use knowledge of “endo angle constraints” to predict that only capsids of specific sizes ($T \geq 7$) possess the potential to undergo true buckling transitions. Interesting inferences on the requirement of auxiliary proteins in large capsids are also discussed in the context of hexameric flexibility.

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*For example, the average dihedral angle value per capsid will tend towards 180° as we proceed to larger and larger capsid sizes.

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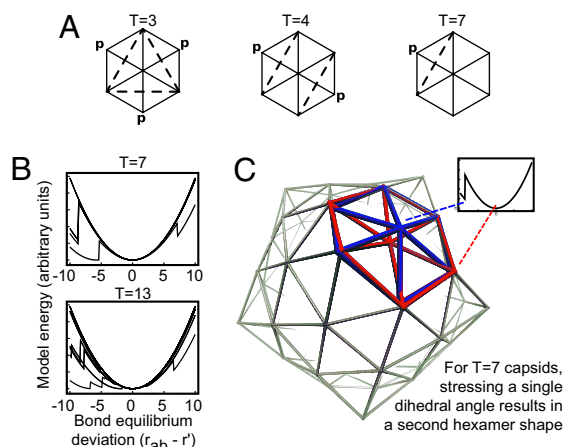


Fig. 4. Only $T \geq 7$ capsid models appear to “buckle.” Hexamer graphs taken from various capsid sizes (where subunits are represented as solid-edged triangles) show that, geometrically, only hexamers from $T = 7$ canonical capsids (or larger) may undergo changes in shape while maintaining monohedrality (see *Endo Angles and Buckling Transitions*). (A) This occurs in light of the endo angle constraints (shown effectively as dashed edges) imposed by pentamers (marked by P). (B) Forces applied onto individual dihedral angles within capsid models (see *Materials and Methods*) indicate that $T < 7$ capsid models are geometrically rigid upon application of small forces on dihedral angles (indicated by parabolic force-energy profiles and singular minima, shown in Fig. S3), whereas the geometry of $T \geq 7$ capsids appear to allow for specific dihedral angles to sample multiple values (shown here for $T = 7, 13$). (C) The result, especially for $T = 7$ capsid models, is that hexamers within the capsid are able to sample 2 distinct configurations (blue and red hexamers), a result that parallels buckling transitions in theoretical (26) and experimental studies of the $T = 7$ capsid (22, 23).

“turned on,” i.e., if the dashed lines are treated as solid (locking certain dihedral angles at $\approx 138.19^\circ$), only certain hexamers (possessing 1 or fewer endo angle constraints) will be allowed to sample at least 2 easily obtainable but distinct configurations. Specifically, those “flexible” hexamers must belong to $T \geq 7$ capsids, where the average endo angle per hexamer $[6/(T - 1)]$, is ≤ 1 . In this way, although endo angles do not directly constrain all angles in the hexamer (via the arrow depiction in Fig. 3A), in some sizes ($T = 3, 4$), all hexameric dihedral angles are effectively constrained because of specifically arranged endo angle constraints.

To test this idea, we looked for the availability of accessible conformations to a capsid by physically perturbing (“squeezing and stretching”) dihedral angles within capsid models (deltahedra) of varying sizes (T numbers). The main assumption is that if the simplistic model is not able to sample alternative configurations, then the all-atom capsid that is constrained by simple geometry certainly will not. Here, the trimers are treated as rigid units (forming equilateral triangles, faces of the deltahedron). This is a reasonable assumption if subunit shapes are not greatly changed upon capsid buckling [as is noticed in the bacteriophage HK97, where the morphology change has little effect on the general shape of the subunit (23) while greatly modifying the hexamer pucker state (22)].

For each dihedral angle, we applied stretching and squeezing forces (that try to expand and contract the dihedral angles, discussed in *Materials and Methods*). The forces were incremented from 0 in small steps (0.00125ϵ units, with cumulative forces ranging from 0 to $\epsilon/8$, where ϵ is the bonded force constant of each bond/edge of the deltahedron), while minimizing the structure at every step. If there is no physical constraint geometrically placed on the specific hexameric angle (on account of the architecture of the model), then the forces will cause a change in the structure, and the recorded energy will remain at

zero. If constrained, the capsid will be relatively unyielding to the forces, and the energy will increase harmonically with each step only to fall back into its original state after forces are lifted. Dihedral angle tests showed that all hexameric dihedral angles within the $T = 1, 3$, and 4 capsids are rigid/constrained within our force regime.

However, analysis of the $T = 7$ capsid model—where the number of endo angles per hexamer is 1 [i.e., where $6/(T - 1) \leq 1$ —shows that some hexameric angles are able to sample an alternative conformation (indicated by the availability of multiple local minima and hexamer configurations in Fig. 4A and B, respectively). The change is not instantaneous upon application of infinitesimal force, but depends on overcoming a small energy barrier (akin to going through a transition state). Our results indicate that buckling transitions that require the sampling of 2 distinct conformations may be available only to $T \geq 7$ capsids (as evidenced in our $T = 7, 13$ models). However, we stress that not all large capsids may possess this ability even at a simple geometric level. For example, the $T = 9$ capsid/deltahedron, which is purely icosahedral in shape (with 20 triangulated facets of 27 subunits), may not possess the ability to easily sample multiple configurations on account of its idealized icosahedral shape (which is purely convex and hence geometrically highly stable).

It is noteworthy that buckling of capsids represented by continuum elastic shells have been performed before, where interesting relationships between radius, capsid size, and sphericity were established (24, 25); however, in these studies, the predictions made have yet to be applied to capsids of specific T numbers. The continuum models neglect molecular/geometric features of the capsid (such as hexamer shape), and are therefore not analogous to our investigations, which are centered around subunit-shape-resolved models. It will be interesting to see whether inferences/predictions from continuum and geometric methods converge.

Buckling Transitions Versus Other Maturation Events. We distinguish between what we call “true” buckling transitions and other maturation events such as capsid swelling (or its inverse: shrinking). Buckling transitions are those transitions that allow a shell to sample 2 morphologies—one being more “spherical” and the other being more “faceted” or icosahedral—without undergoing major changes in subunit–subunit bondedness and subunit shape (23). This excludes the other kind of maturation events—swelling (27–29)—which is theoretically available to any capsid regardless of size. Also, those maturation events requiring gross change in subunit shape [e.g., as seen in Flaviruses (30)] are not considered here.

Swelling is primarily caused by weakening of interfaces (via pH modulation, ion depletion, electrostatic screening, etc.), which causes a radial capsid swell (its converse, “shrinking,” happens when subunit–subunit interactions are strengthened). These events often accompany the introduction/removal of holes between subunits (commonly found within trimers), which cannot be modeled by simple monohedral tilings/deltahedra (as holes must be considered as additional tiles). Examples of swelling and shrinkage are the $T = 3$ and unnatural $T = 1$ plant viruses such as sesbania mosaic virus (that undergo swelling) (27, 31) and $T = 4$ semliki forest virus and $T = 16$ herpes virus (that undergo shrinkage from a swollen precursor to a finally more icosahedral-looking capsid) (28, 29), all of which display holes in their expanded or swollen forms. These kinds of swelling/shrinking transformations comprise radial motions that have been given previous theoretical consideration (32, 33) and were not considered here.

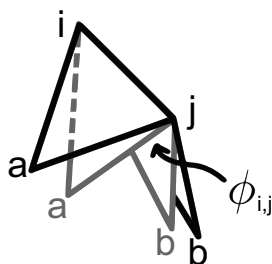


Fig. 5. The dihedral angle $\phi_{i,j}[\text{infin}]$ between 2 equilateral faces sharing edge $\{i,j\}$ (shown in 2 configurations) depends on the distance between a and b (r_{ab}).

$$E_c = \frac{1}{2} k_c (r_{ab} - r'_{ab})^2.$$

It is imperative that the force constant $k_c \ll k_{\text{rest}}$, where k_{rest} is the strength of the bonds making up the deltahedron. This is required because we are

studying elastic deformations of dihedral angles (and the dihedral bond) and not the equilateral faces of the deltahedra (although small deviations in shape are acceptable).

We assayed the effect of applying stress onto a dihedral angle with respect to resulting energy change. The study is performed by using the following algorithm:

Initialization step. (i) Identify the edge $\{i,j\}$ whose dihedral angle is to be studied. (ii) Assign a restraint energy term E_c as shown above to the appropriate atom pair ($\{a,b\}$, in Fig. 5). (iii) Assign $r'_{ab} = r_{ab}$, where r_{ab} is the length between atom pair $\{a,b\}$ in initially obtained (embedded) deltahedron. This ensures that at the first step all energy terms equal zero (because the deltahedron is minimized).

Cycle (until $|r'_{ab}| \leq |r'_{\text{max}}|$). (i) Assign $r'_{ab} = r'_{ab} + \text{step_size}$. This will cause a force to be applied onto a and b because the $\{a,b\}$ bond length will not be at its equilibrium value. (ii) Allow the structure to relax by energy minimization. At this point, we obtain the total energy of the new structure.

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Supporting Information

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SI Text

To show that canonical intrapentameric dihedral angles interact at $\approx 138.19^\circ$: Hexamers and pentamers within a canonical capsid (those capsids representable as “monohedral tilings” that display few holes, few overlaps and structural invariability; please see ref. 1 for a more rigorous description) may be treated as a 6- and 5-coordinated set of plates, respectively (Fig. S2 A–C).

Statement. Any canonical subunit that possesses the ability to form both pentamer and hexamer must possess intrapentamer dihedral angles of $\approx 138.19^\circ$ (i.e., in Fig. S2D, $\phi \approx 138.19^\circ$).

From the canonical capsid definitions (1), we find that (i) subunits can form both flat hexamers (Fig. S2B) and “curved” pentamers (Fig. S2C) from the same interface and (ii) all angles within a pentamer are identical [which is a reasonable assumption given that (i) these pentameric angles are formed from identical interfaces and not quasiequivalent ones and (ii) a 5-fold rotational symmetry element (axis) falls perpendicular to the center of pentamer in the crystal structure].

Proof. Specifically, from the right triangle $b'o'a$ in Fig. S2D, we can obtain a relationship for the intrapentamer dihedral angle (Φ) and edge lengths:

$$\sin(\phi/2) = \frac{|o'a|}{|ab'|} \quad [\text{S1}]$$

We now assume that the edge of the equilateral triangular faces is 1 with no loss of generality. Given that right triangle $ab'o$ is a 30–60–90 triangle and that $|oa| = 1$, we get

$$|ab'| = \sqrt{3}/2 \quad [\text{S2}]$$

Substituting Eq. S2 in Eq. S1 and rearranging, we get

$$\sin(\phi/2) = \frac{2}{\sqrt{3}} |o'a| \quad [\text{S3}]$$

Theta (θ) is the angle between the adjacent radiating edges once projected to a plane that contains a,b,c,d,e (there must be such a plane because all dihedral angles are set to the same value). From Fig. S2D, we get

$$|o'a| = |o'a|\sin(\theta) \quad [\text{S4}]$$

Substituting Eq. S4 into Eq. S3, we get

$$\sin(\phi/2) = \frac{2}{\sqrt{3}} |o'a|\sin(\theta) \quad [\text{S5}]$$

Also, from the 30–60–90 triangle $o'aa'$ in Fig. S2C, because $|aa'| = 1/2$, we obtain

$$|o'a| = \frac{|a'a|}{\sin(\theta/2)} = \frac{1}{2\sin(\theta/2)}. \quad [\text{S6}]$$

Substituting Eq. S6 in Eq. S5 yields

$$\sin(\phi/2) = \frac{\sin(\theta)}{\sqrt{3}\sin(\theta/2)} \quad \text{or} \quad \phi = 2 \cdot \text{asin}\left(\frac{\sin(\theta)}{\sqrt{3}\sin(\theta/2)}\right). \quad [\text{S6'}]$$

If all of the dihedral angles within the pentamer are alike, then $\theta = 2\pi/5$ (this generalizes to $\theta = 2\pi/i$ if the pentamer is actually an i -mer), and

$$\phi = 2 \cdot \text{asin}\left(\frac{\sin(2\pi/5)}{\sqrt{3}\sin(\pi/5)}\right) \approx 138.19^\circ.$$

This will be true for any set of canonical capsid subunits that assemble into pentamers, and is also seen in true icosahedra (20-faced deltahedra) that describe $T = 1$ capsids, which, we claim, allows for $T > 1$ to $T = 1$ transformations (see main text).

1. Mannige RV, Brooks CL, III (2008) Tilable nature of virus capsids and the role of topological constraints in natural capsid design. *Phys Rev E* 77:051902.27.

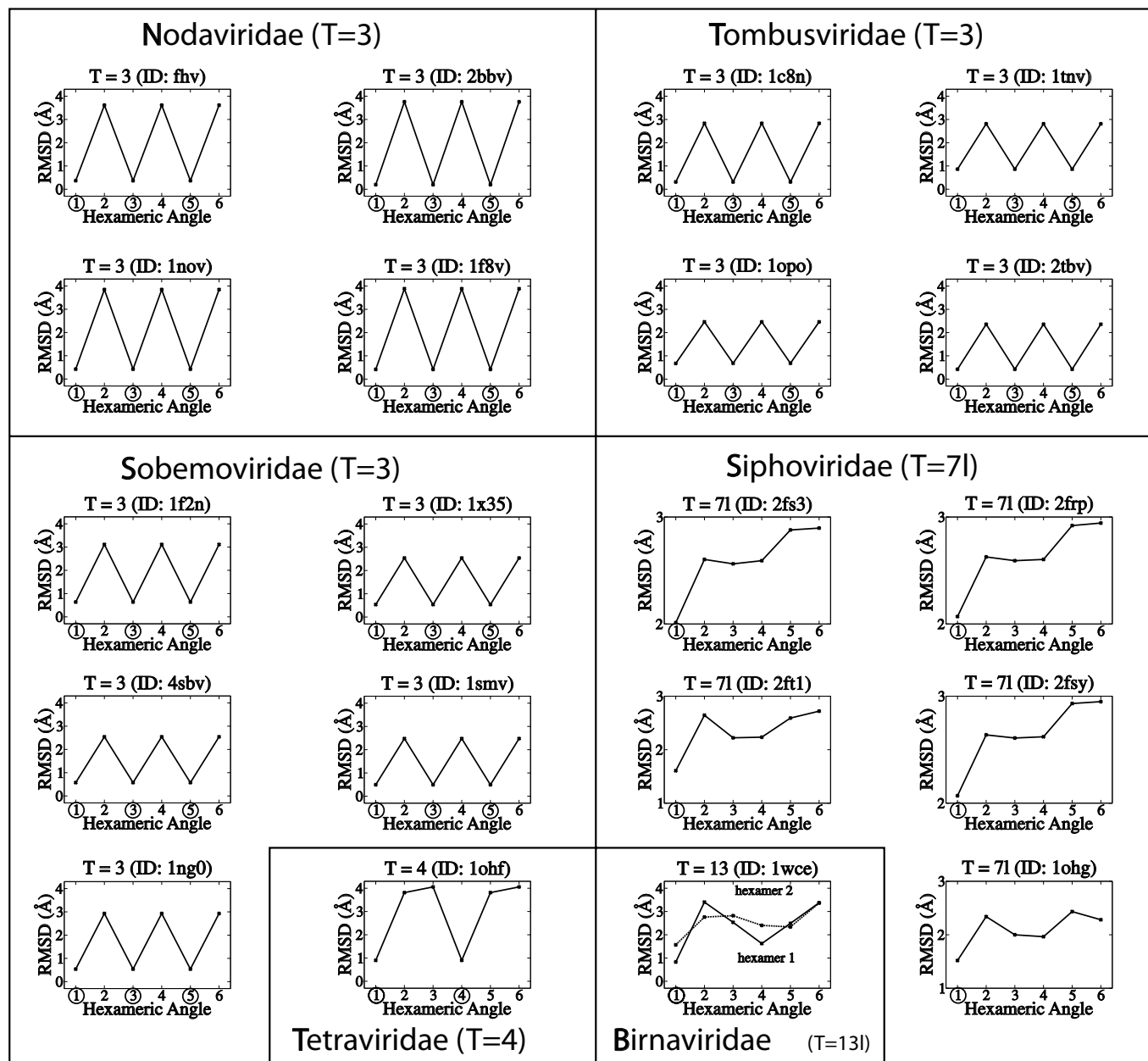


Fig. S1. Angle profiles of hexamers in unique environments when compared to a pentameric endo angle of the same capsid (low RMSD values indicate more pentamer-like angles) shown for individual capsids (indicated by their PDB ID or ID). This graph is an expanded version of Fig. 2A.

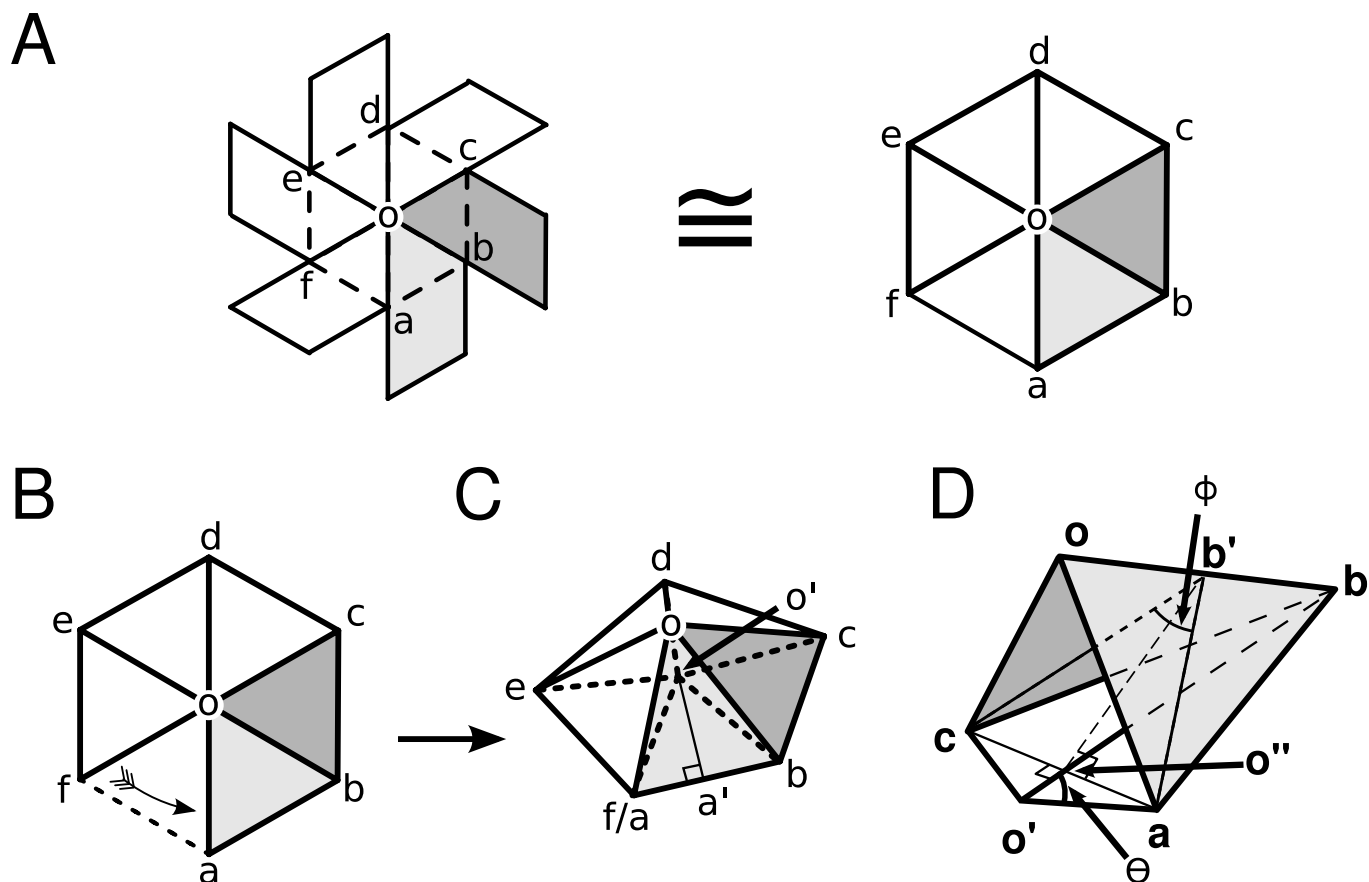


Fig. 52. Showing that $\Phi = \approx 138.19^\circ$. (A) Indicates that n -valent clusters formed from trapezoids (shown in the diagram for hexamers) may be reduced/simplified to clusters of equilateral triangles for the purpose of analyzing dihedral angle properties. (B and C) Hexamers (B) and pentamers (C) in canonical capsids are formed from the same subunit interface that interact at varying dihedral angles. (D) A pair of adjacent subunits is shaded in the pentamer (C) and isolated environment (D), which will be used to obtain a relationship for the dihedral angle (Φ).

